# Google Transducer-Based Streaming Deliberation For Cascaded Encoders Ke Hu, Tara N. Sainath, Arun Narayanan, Ruoming Pang, Trevor Strohman, Google LLC, USA

# 1. Introduction

- Deliberation models improve ASR as 2nd pass rescoring or decoding [1, 2]
  - 1st pass is typically an RNN-T
  - However, 2nd pass deliberation is often based on attention decoders and does not stream

### Streaming Deliberation

- Streaming models are user friendly
- We use a Transducer Decoder for deliberation
  - Ist-pass hypotheses streamed by a transducer
  - 2nd-pass attends to streamed partial 1st-pass hypotheses, and feed to 2nd-pass joint layer as an additional input
- The whole model naturally streams
- Novelty
  - Encode first-pass results as a context for 2nd pass decoding
  - Incremental processing instead of requiring full-context for deliberation

# 4. Experiment Details

### Model Architecture

- Based on conformer transducer with cascaded encoders [3]
  - 17 causal + 4 non-causal layers (2.88s right context)
- Deliberation
  - Text encoder: 2-layer 640-D conformer (2.88s right) context)
  - Joint layer: Sum encoded audio, prediction network output, and attention
- Inputs and Outputs
  - 32-ms window with 10-ms frame rate
  - Stack previous 3 frames to form 512-D log-Mel features and downsample to 30ms rate
  - Outputs to predict 4,096 lowercase wordpieces

# • Datasets

- Training: ~400k hours from multiple domains
- Test Sets
  - Short-from (15K utts)
  - TTS utterances: App (16K), Song (15K), Contacts (15K)
    - Contain proper nouns such as app names, song names, and personal contact names



WER (%)					
	Song	Contacts	Avg.		
1	14.8	38.8	20.4		
a Q	11.5	27.3	15.7		
	11.9	27.1	16.1		
	10.3	24.7	14.5		
6	-10.4%	-9.5%	-7.6%		

Deliberation			
vords express open			
google adsense			
the wearos phone			
ress meditation okay			

Model	B2	E2
RWER (%)	8.3	8.0

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• 1st pass naturally streams because it is a transducer

Non-Causal Encoder streams with a latency equal

• **Deliberation:** Encode 1st pass hypothesis

incrementally and attend to partial sequences

• Use a right-context conformer as text encoder

• For *i*th non-blank token, the right-most frame we need to encode is:  $r_i = min(t'_{i+R}, T')$ 

R: conformer right-context T': maximum time frame of any token  $t_{i+R}$  : time frame of the non-blank token distance R to the right of i

• At time *t*, only look ahead *A* frames to get a partial sequence:

 $e_y(t) = \{e_{y,k} | \text{ where } r_k < t + A \text{ and } k < L\}$ 

A: attention lookahead  $r_k$ : right-most frame to encoder kth token

**3. Transducer decoder** naturally streams

**Overall latency is from** *R* **and** *A* **(**choose A=R and parallelize)

# 6. Conclusion

# WER

• Transducer deliberation improves WER by 3.6% - 10.4% for various long-tail scenarios compared to cascaded encoder [2]

# Latency

• The model does not introduce extra latency on top of the cascaded encoder

# References

- [1] Hu et al., <u>Two-pass deliberation</u>, 2020
- [2] Hu et al., <u>Transformer deliberation</u>, 2021
- [3] Narayanan et al., <u>Cascaded encoders</u>, 2021